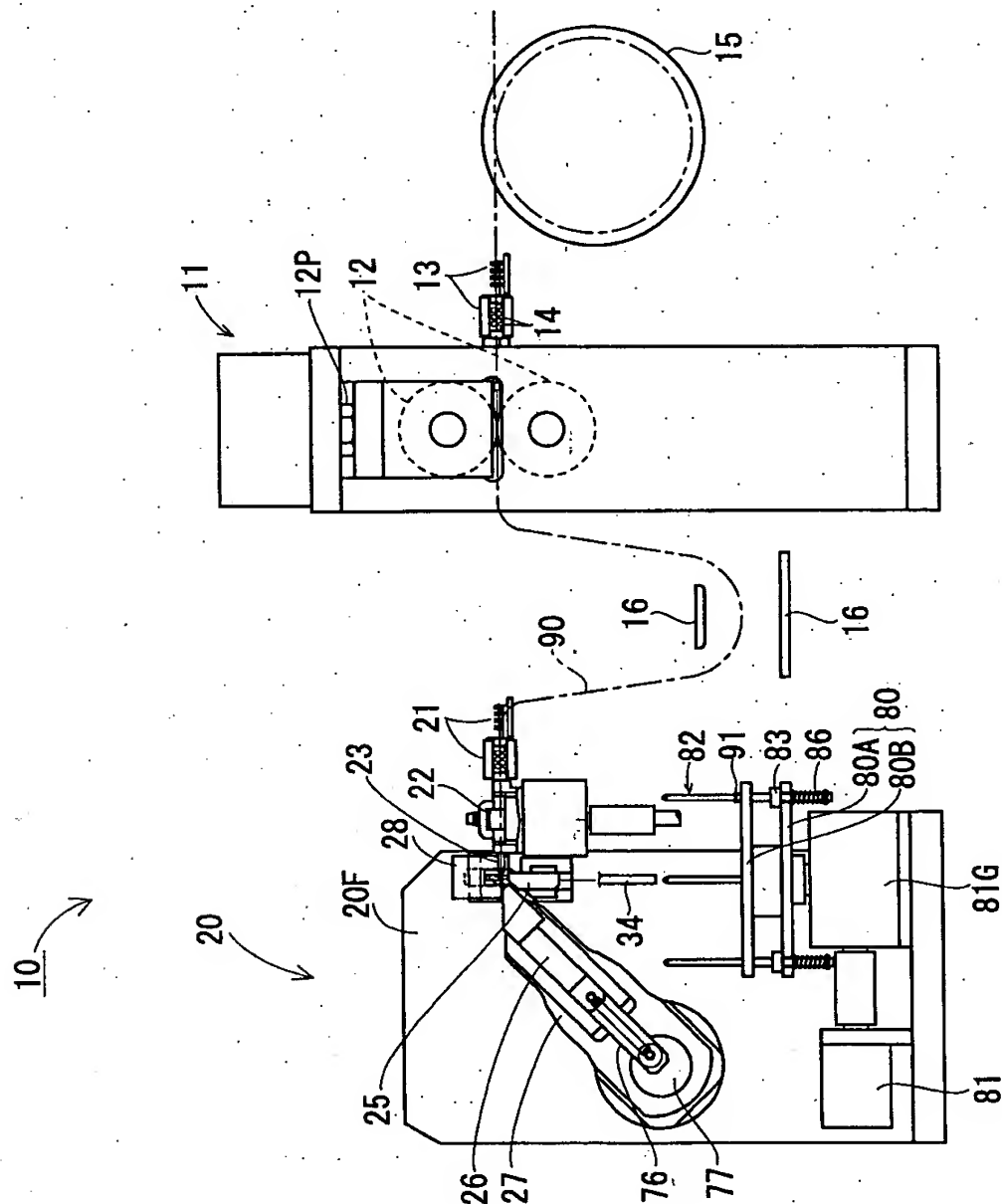


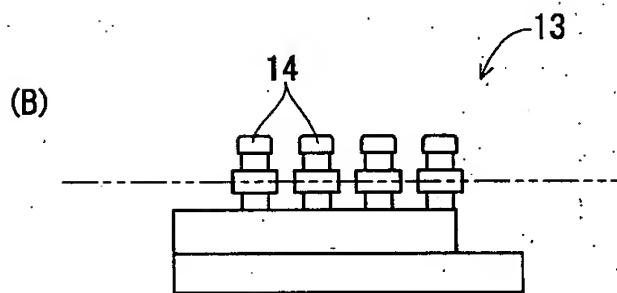
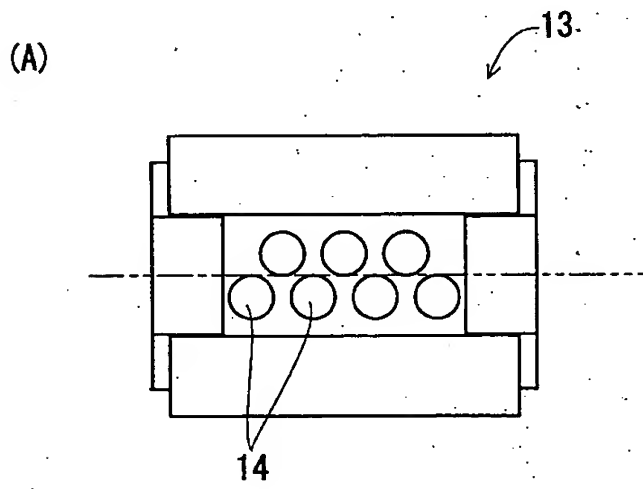
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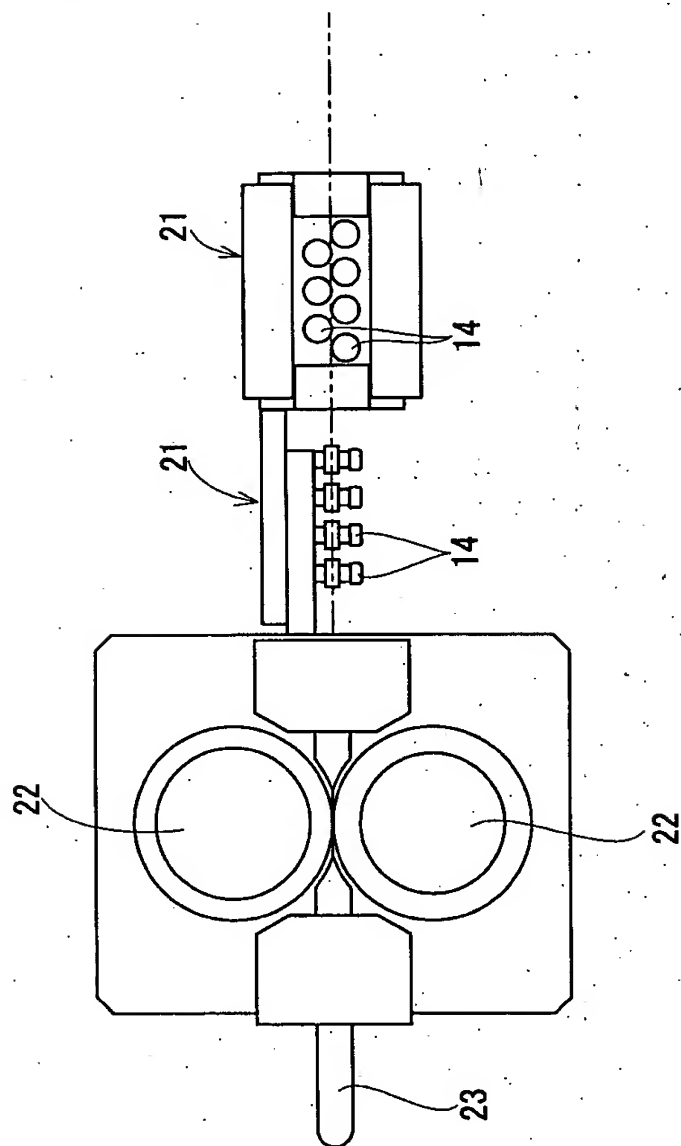
【図1】



【図2】



【図3】



【図4】

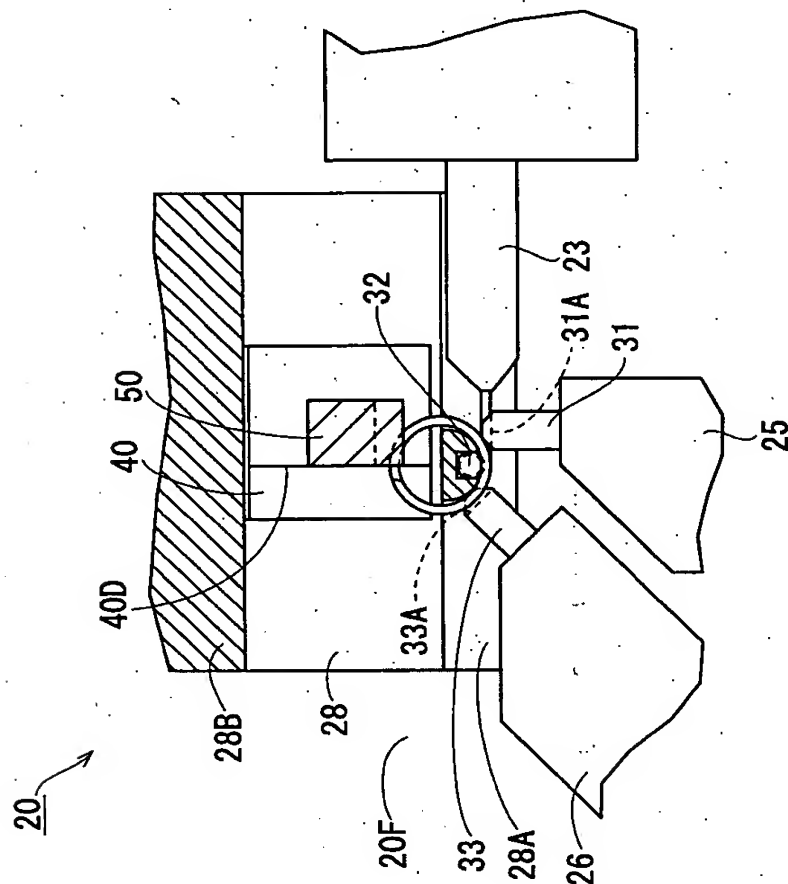
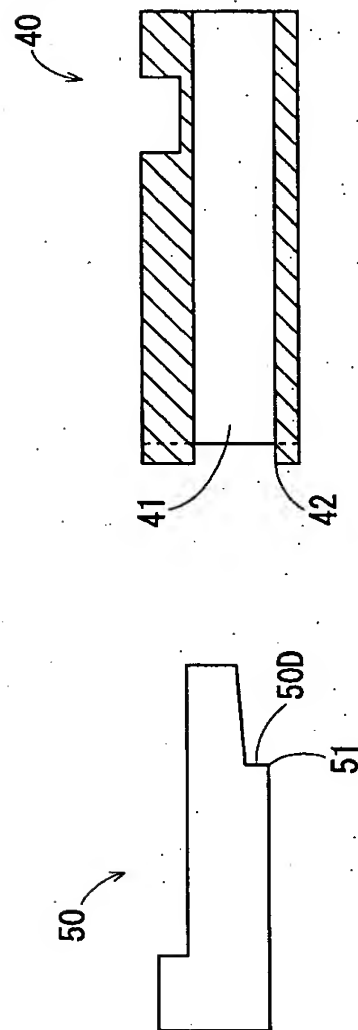
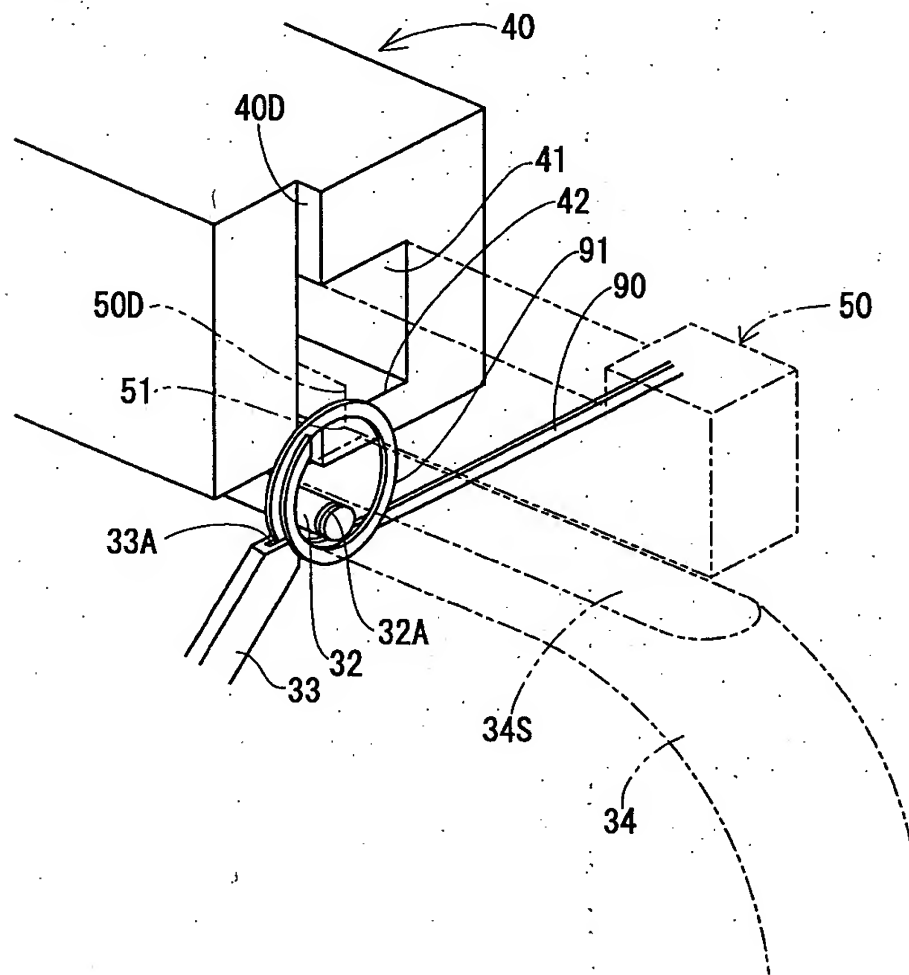


FIG. 2 is a cross-sectional view of the device in a second state. The sliding member 28 has moved to the right, as indicated by the arrow labeled 'A'. This movement causes the locking member 34 to engage with the sliding member 28, preventing further movement. The locking member 34 is shown in a retracted position, with its tip 34S now positioned behind the sliding member 28. The locking member 34 is connected to the base 32 via a linkage mechanism 34M. The base 32 is shown in a cross-sectional view, with the locking member 34 being a separate component that can move relative to the base. The sliding member 28 is shown in a cross-sectional view, with its top surface 28A and bottom surface 28B. The base 32 is shown in a cross-sectional view, with its top surface 32A and bottom surface 32B. The locking member 34 is shown in a cross-sectional view, with its tip 34S and its base 34M. The locking member 34 is connected to the base 32 via a linkage mechanism 34M. The base 32 is shown in a cross-sectional view, with the locking member 34 being a separate component that can move relative to the base. The sliding member 28 is shown in a cross-sectional view, with its top surface 28A and bottom surface 28B. The base 32 is shown in a cross-sectional view, with its top surface 32A and bottom surface 32B. The locking member 34 is shown in a cross-sectional view, with its tip 34S and its base 34M. The locking member 34 is connected to the base 32 via a linkage mechanism 34M.

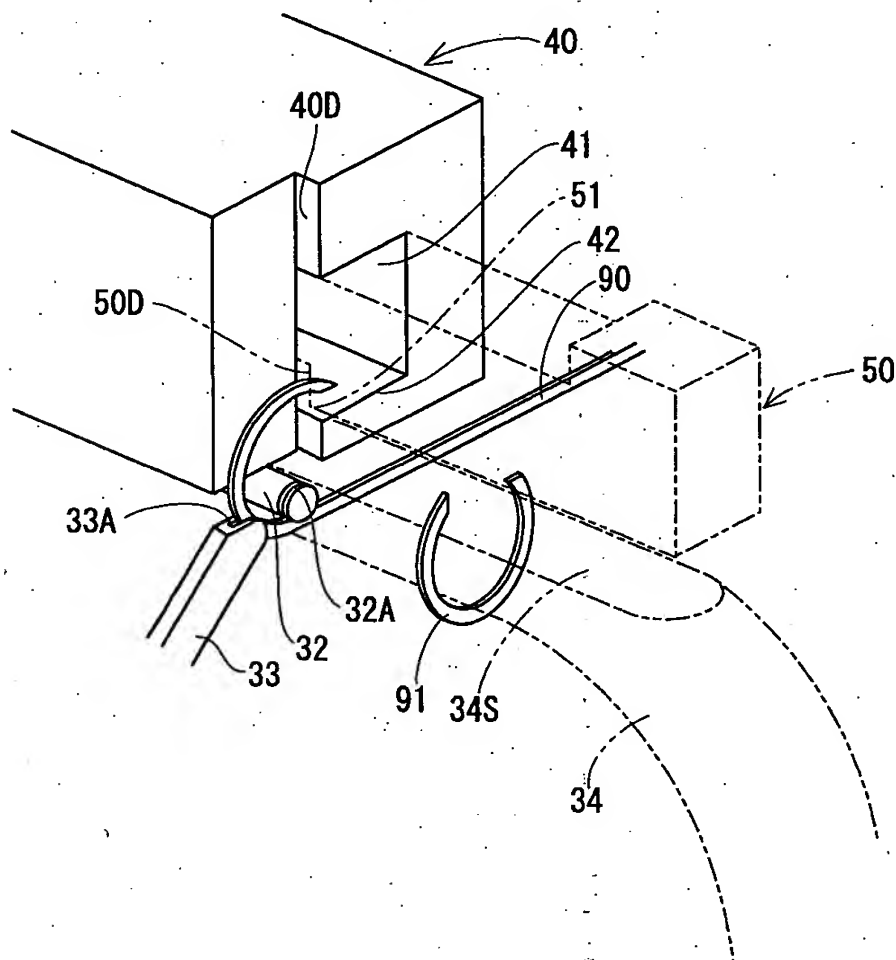
【図 6】



【図7】

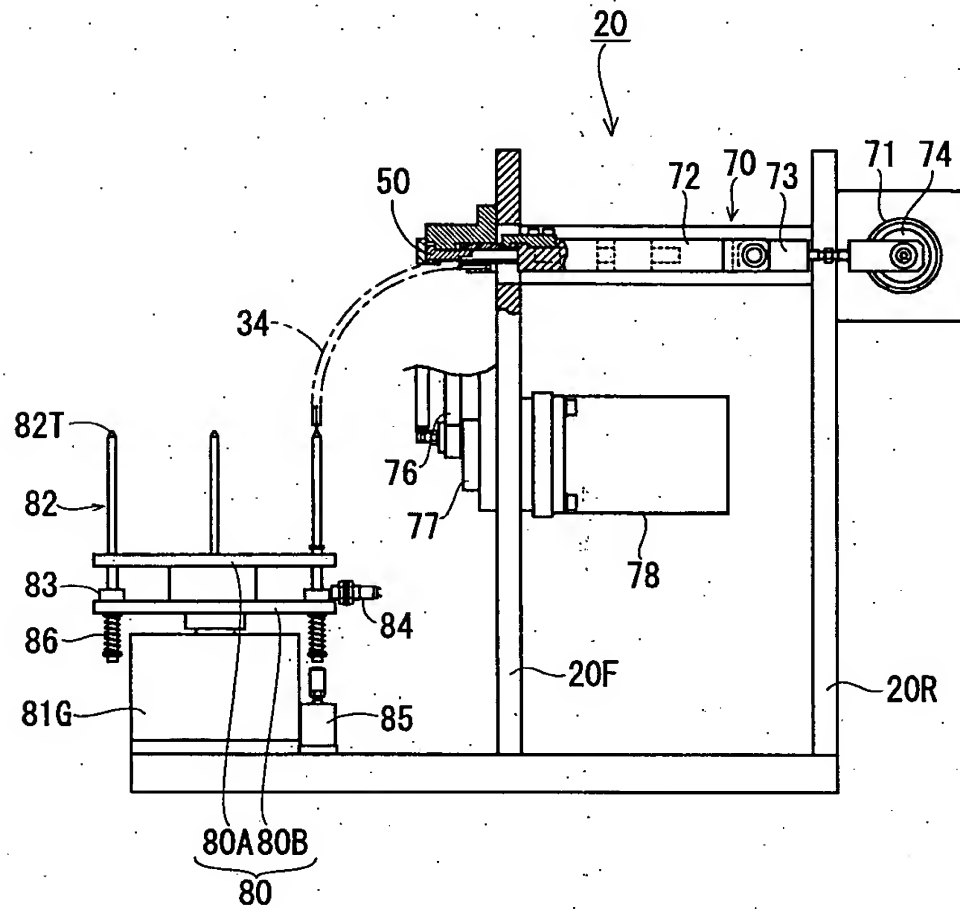


【図8】

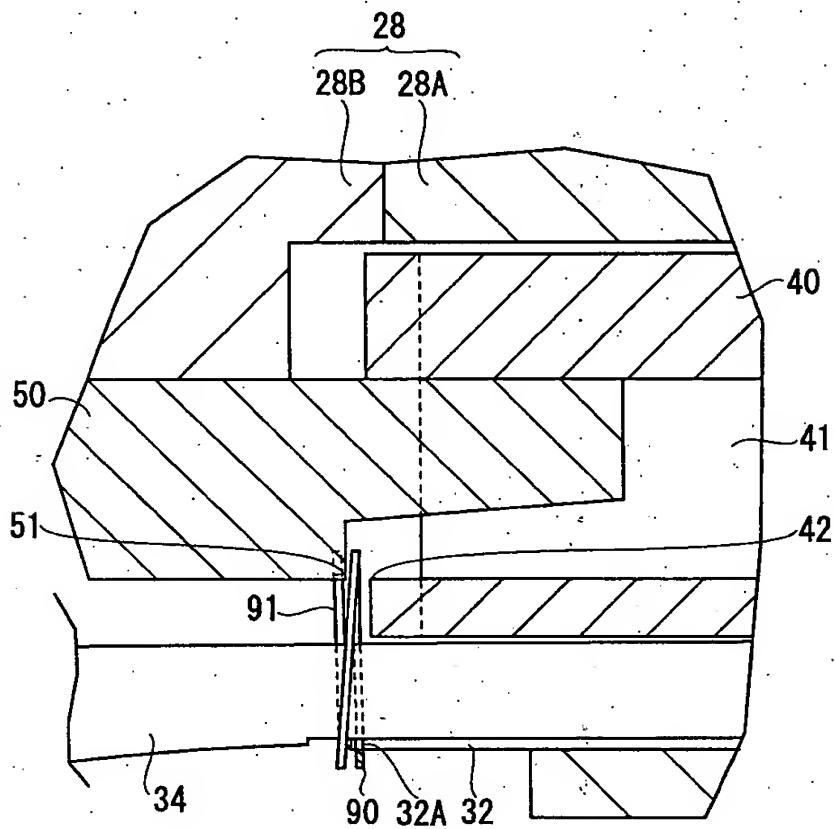




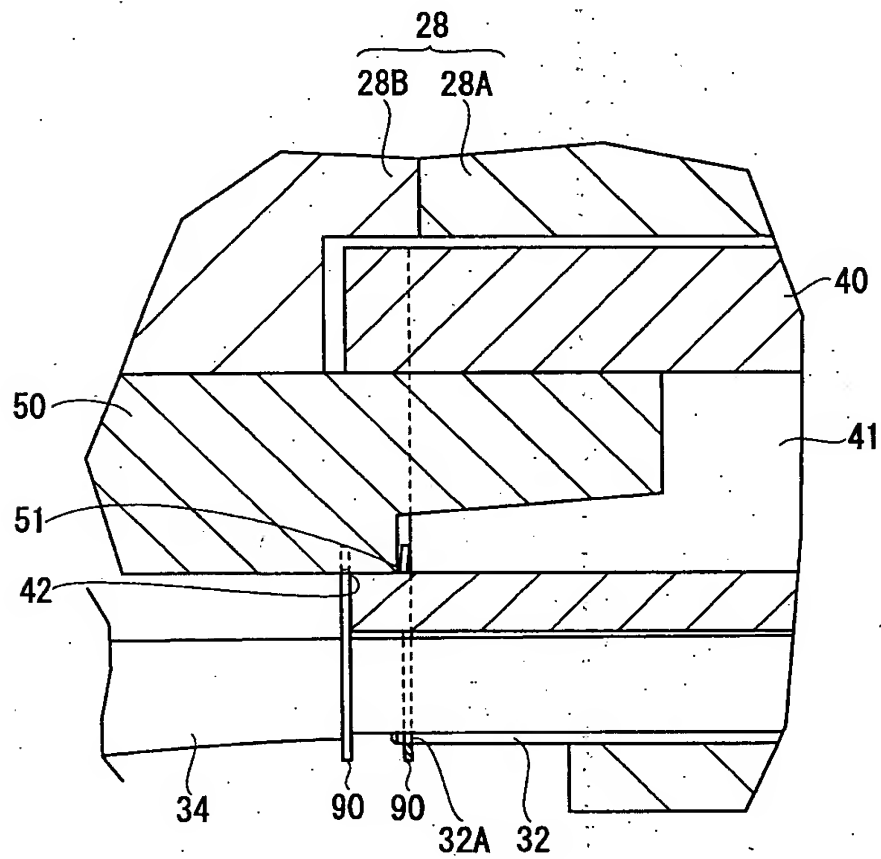
【図9】



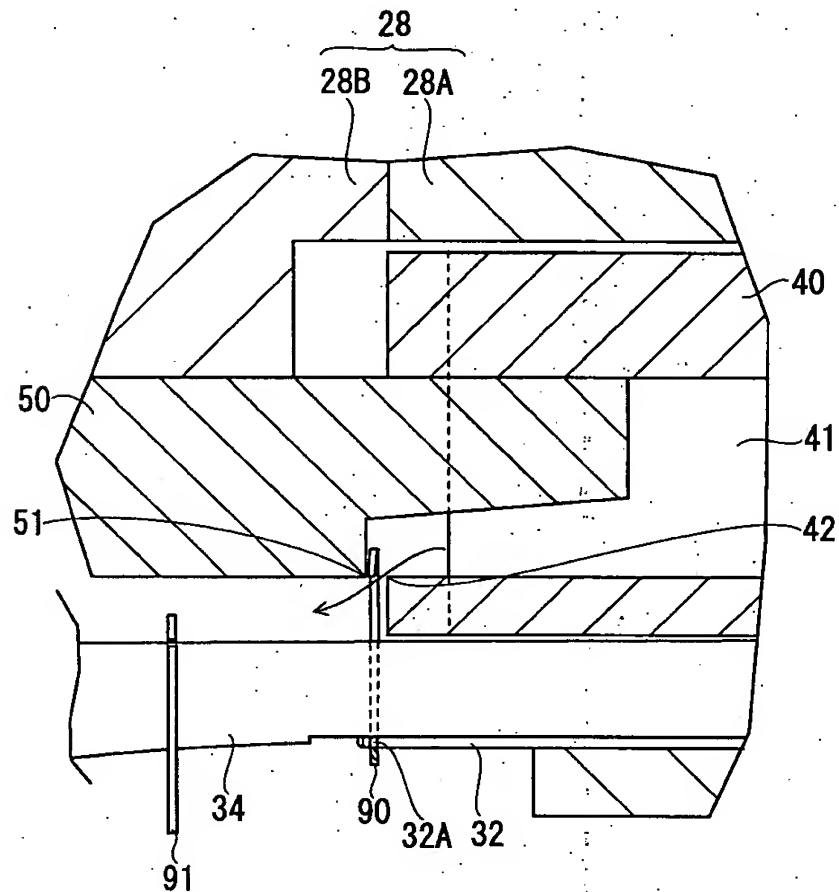
【図10】



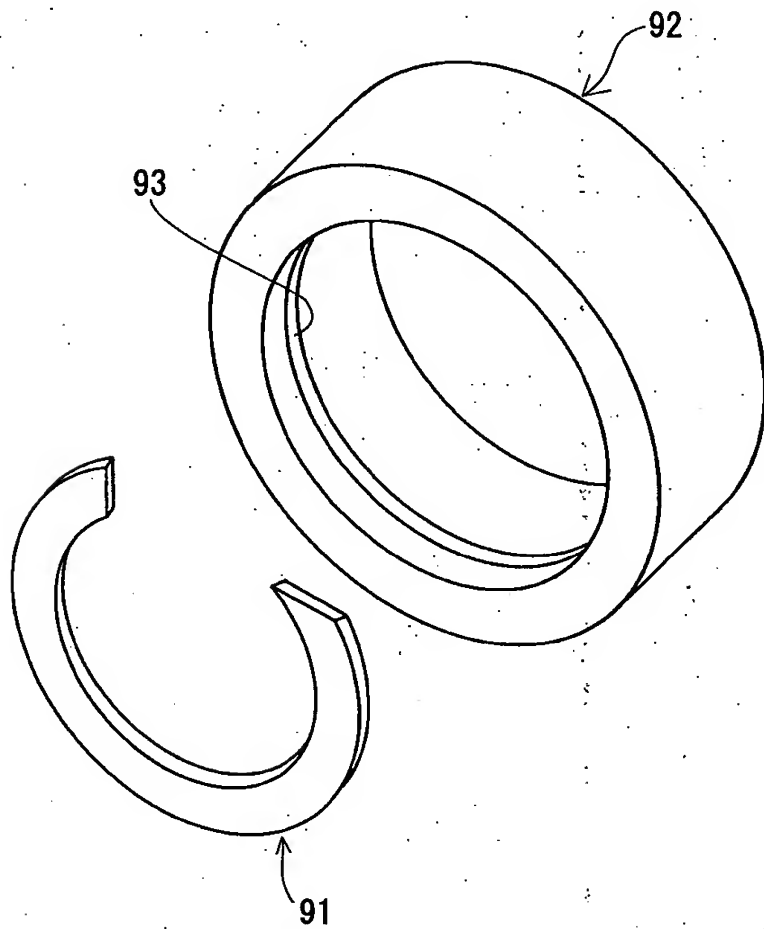
【図11】



【図12】



【図13】



【図14】

